

A Metric Learning Approach to Graph Edit Costs for Regression

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Overview

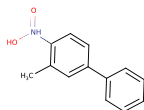
- 1 Introduction
- 2 State of the art
- 3 Proposed method
- 4 Experiments
- 5 Conclusion and future work

Graph data

Original data

Graph representation

chemoinformatics: molecule



social media: social network



computer vision: handwriting



Original data

Graph representation

computer vision: 3D point cloud



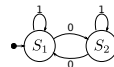
knowledge graph



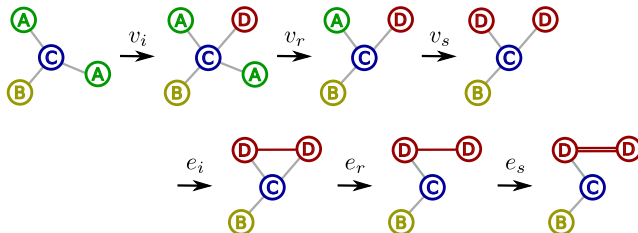
state transition

State-transition table

Current state \ Input	Input	
	0	1
S ₁	S ₂	S ₁
S ₂	S ₁	S ₂



Graph edit distances



$$(v_{i_0}, v_{r_0}, v_{s_0}, v_{s_1}, v_{r_1} \dots) \rightarrow \pi \longrightarrow \text{ged}(G_1, G_2) = \min_{\pi_1, \dots, \pi_k \in \Pi(G_1, G_2)} \sum_{i=1}^k c(\pi_i)$$

$$\begin{cases} \mathbf{x} = [n_{vr}, n_{vi}, n_{vs}, n_{er}, n_{ei}, n_{es}]^T \\ \mathbf{c} = [c_{vr}, c_{vi}, c_{vs}, c_{er}, c_{ei}, c_{es}]^T \end{cases} \longrightarrow \text{ged}(G_i, G_j) = \mathbf{x}^T \mathbf{c}$$

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Methods to learn edit costs

- **Set manually (expert costs):**

- domain knowledge implied a priori
- costs required in datasets
- data information not well explored
- hard to generalize

- **Learn costs:**

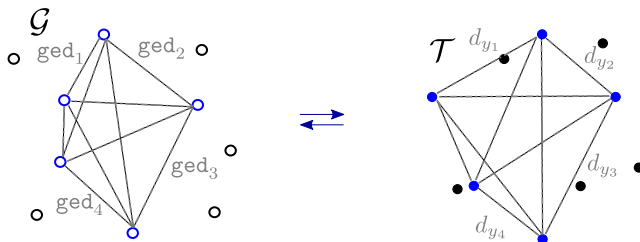
- high computational complexity
- restricted to strings and trees
- require a ground truth mapping
- literature on metric learning for graph data is limited

-> Our method: Learn edit cost by aligning GEDs and distances between targets.

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Align graph space and the target space



$$ged_1 = d_{y1}, \quad ged_2 = d_{y2}, \quad ged_3 = d_{y3}, \quad ged_4 = d_{y4}, \quad \dots$$

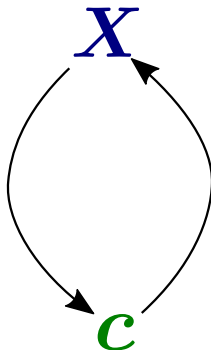
$$\begin{cases} ged(G_i, G_j) = \mathbf{x}^\top \mathbf{c} \\ d_y(G_i, G_j) = \|y(G_i) - y(G_j)\|_2 \end{cases}$$

$$\longrightarrow \arg \min_{\mathbf{c}, \mathbf{x}} \sum_{i,j=1}^N \left(ged^{i,j} - d_y^{i,j} \right)^2$$

Align graph space and the target space

$$\arg \min_{\mathbf{c} > 0} \|\mathbf{X}^\top \mathbf{c} - \mathbf{d}_y\|^2$$

CVXPY, scipy



→ $\mathbf{c}_{\text{optimized}}$

$\forall G_i, G_j,$
 $\text{ged}(G_i, G_j) = \mathbf{x}(i, j)^\top \mathbf{c}$
 bipartite, IPFP

- $\mathbf{X}^\top$: the N^2 -by-6 matrix with rows $\mathbf{x}(i, j)^\top$;
- $\mathbf{d}_y$: the vector of N^2 entries $d_y(G_i, G_j)$, for $i, j = 1, \dots, N$.

Overview

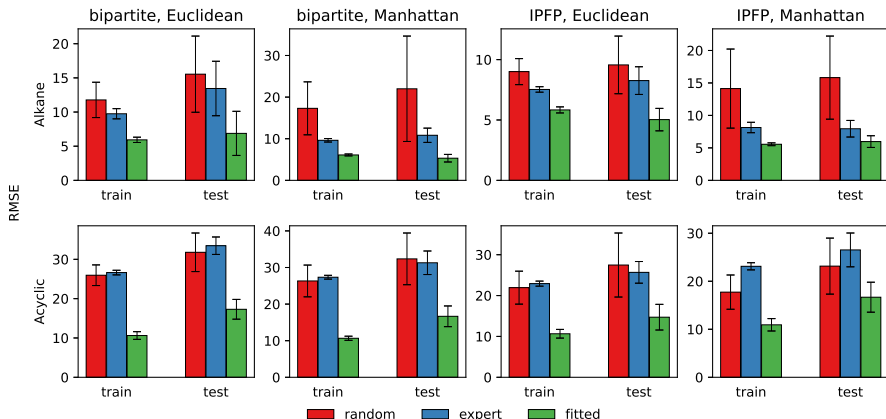
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Experiment settings

- **Datasets:**
 - molecules and their boiling points as targets
 - the Alkane dataset: unlabeled
 - the Acyclic dataset: nodes with discrete labels
- **Configurations:**
 - K-NN regression problem
 - *mbipartite* and *mIPFP* with $m = 40$
 - outer CV: 90% training + 10% test, inner CV: 5-fold
 - k optimized in inner CV over $\{3, 5, 7, 9, 11\}$
 - maximum number of iterations: 5

Performance

Results on each dataset in terms of RMSE for the 10 splits, measured on the training and on the test sets:



Performance

A different representation of the same results:

Dataset	Distance	Method	bipartite		IPFP	
			Train errors	Test errors	Train errors	Test errors
Alkane	Euclidean	random	11.77 $\pm$ 2.59	15.54 $\pm$ 5.58	9.001 $\pm$ 1.08	9.56 $\pm$ 2.39
		expert	9.75 $\pm$ 0.75	13.45 $\pm$ 3.98	7.53 $\pm$ 0.23	8.26 $\pm$ 1.15
		fitted	5.93$\pm$0.39	6.88$\pm$3.23	5.83$\pm$0.25	5.03$\pm$0.93
	Manhattan	random	17.30 $\pm$ 6.36	22.00 $\pm$ 12.66	14.13 $\pm$ 6.09	15.82 $\pm$ 6.40
		expert	9.63 $\pm$ 0.42	10.83 $\pm$ 1.71	8.14 $\pm$ 0.80	7.95 $\pm$ 1.28
		fitted	6.10$\pm$0.23	5.32$\pm$0.91	5.56$\pm$0.22	5.97$\pm$0.90
Acyclic	Euclidean	random	25.96 $\pm$ 2.63	31.79 $\pm$ 4.90	21.94 $\pm$ 4.03	27.48 $\pm$ 7.84
		expert	26.63 $\pm$ 0.59	33.46 $\pm$ 2.22	22.92 $\pm$ 0.62	25.68 $\pm$ 2.65
		fitted	10.62$\pm$0.98	17.29$\pm$2.52	10.66$\pm$1.06	14.71$\pm$3.14
	Manhattan	random	26.33 $\pm$ 4.34	32.36 $\pm$ 7.06	17.73 $\pm$ 3.57	23.15 $\pm$ 5.83
		expert	27.34 $\pm$ 0.52	31.29 $\pm$ 3.22	23.11 $\pm$ 0.74	26.53 $\pm$ 3.52
		fitted	10.66$\pm$0.56	16.66$\pm$2.83	10.93$\pm$1.29	16.68$\pm$3.12

Performance

Table: Average and standard deviation of fitted edit costs values

Dataset	Edit cost	Distance	c_{ni}	c_{nr}	c_{ns}	c_{ei}	c_{er}	c_{es}
Alkane	bipartite	Euclidean	26.45±0.48	26.24±0.60	-	0.13±0.06	0.14±0.09	-
		Manhattan	26.67±0.37	26.63±0.58	-	0.11±0.04	0.11±0.06	-
	IPFP	Euclidean	26.12±0.24	25.88±0.25	-	0.74±0.23	0.78±0.23	-
		Manhattan	25.94±0.38	25.71±0.44	-	0.89±0.30	0.77±0.29	-
Acyclic	bipartite	Euclidean	13.81±0.48	13.83±0.80	10.46±0.40	1.37±0.46	1.45±0.46	1.41±0.09
		Manhattan	13.76±0.39	14.14±0.57	10.28±0.44	1.44±0.20	1.45±0.19	1.45±0.07
	IPFP	Euclidean	11.61±0.45	11.68±0.43	11.07±0.53	4.49±0.30	4.46±0.24	4.48±0.18
		Manhattan	11.52±0.40	11.40±0.40	10.61±0.52	4.50±0.31	4.50±0.31	4.50±0.10

- Insertion and deletion costs are almost similar, hence showing the symmetry of these operations.
- Deletion and insertion costs are more important than substitution costs, which shows that the number of atoms is more important than the atom itself.

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- Conclusion:
 - learn optimal graph edit costs for regression
 - metric learning, space alignment
 - alternated optimization strategy
 - experiments show promising results
- Future work:
 - comparison to other methods
 - other criteria (besides the distance-preserving criterion)
 - convergence proof
 - to classification problem
 - to non-constant costs

Questions

Thank you.

Any questions?